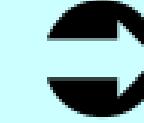


Y_b

X_1

Y_a



Intervention

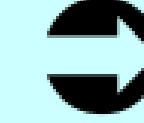


$\sim R$ -----

Y_b

X_2

Y_a



Control